

MathWorks
**AUTOMOTIVE
CONFERENCE 2023**
India

Open Simulation Interface Using RoadRunner For Automated Driving Validation

Anantesh Shet, Aptiv



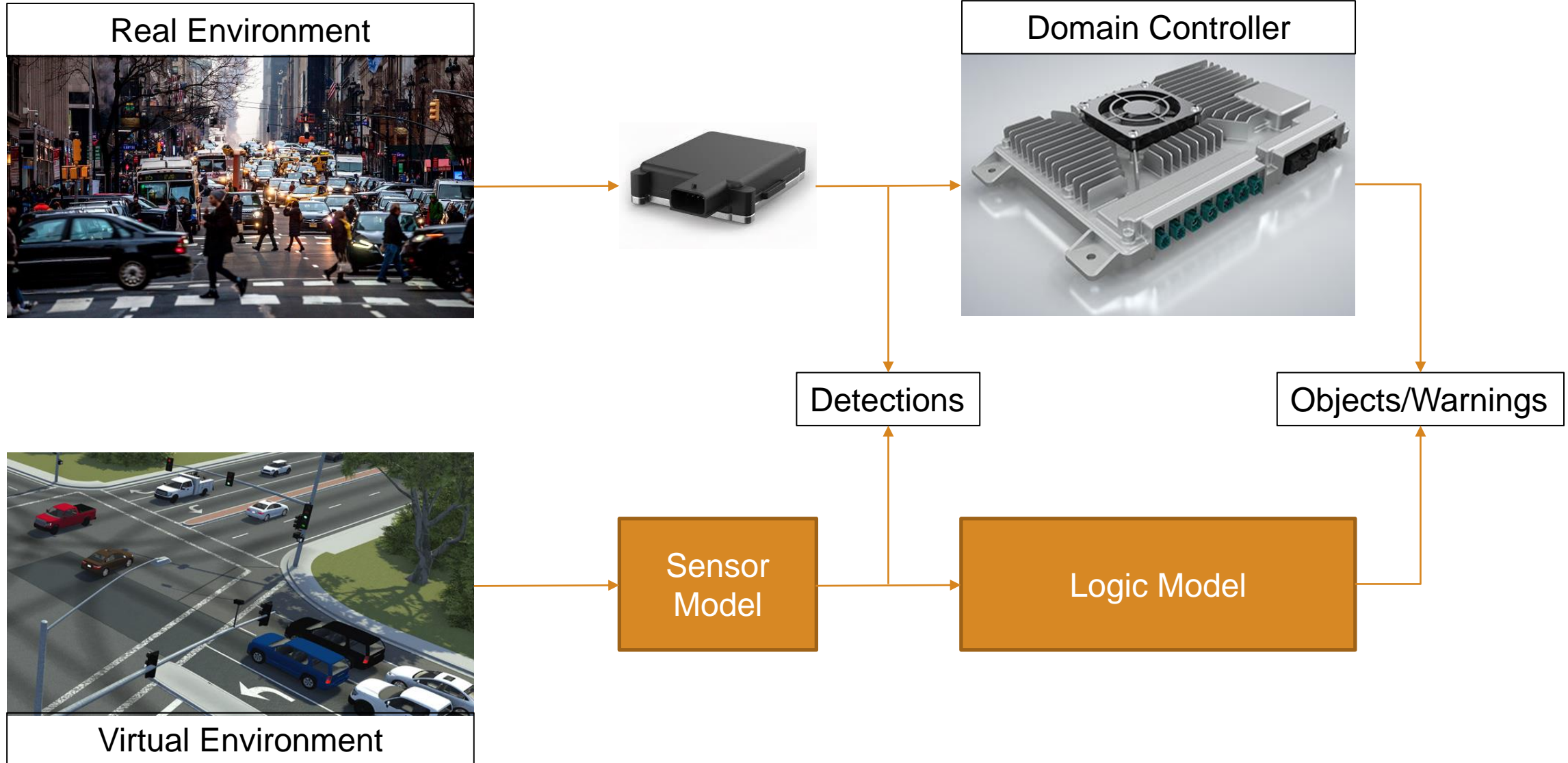
Abhishek UH, Aptiv



Naga Pemmaraju, MathWorks



What is Virtual Simulation?

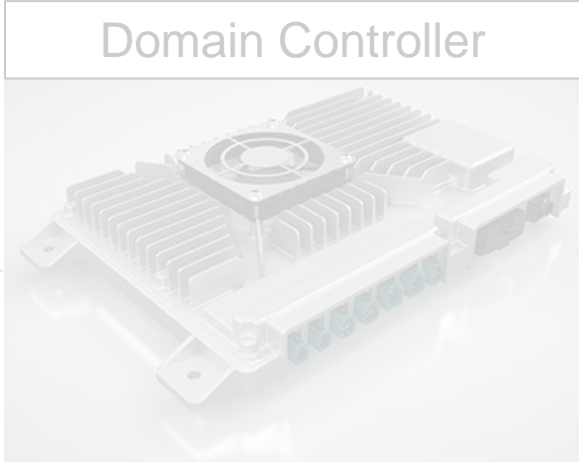




Virtual Environment



Real Environment



Domain Controller

Detections

Objects/Warnings



Virtual Environment

Sensor Model

Logic Model

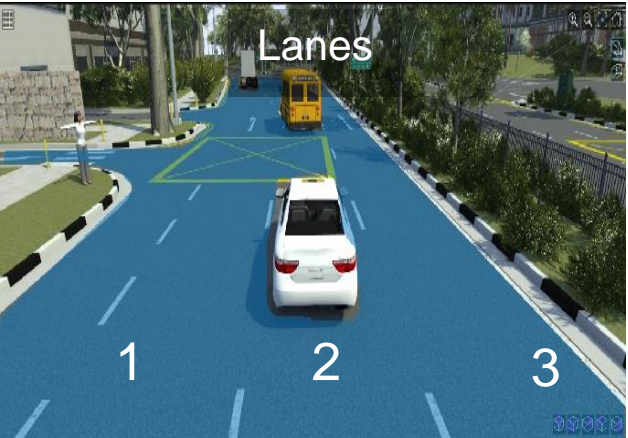
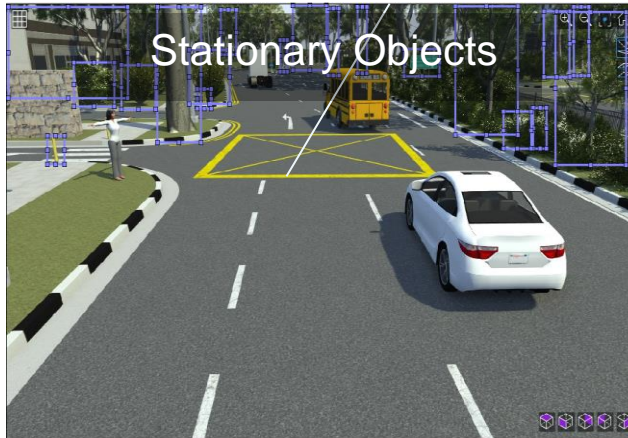
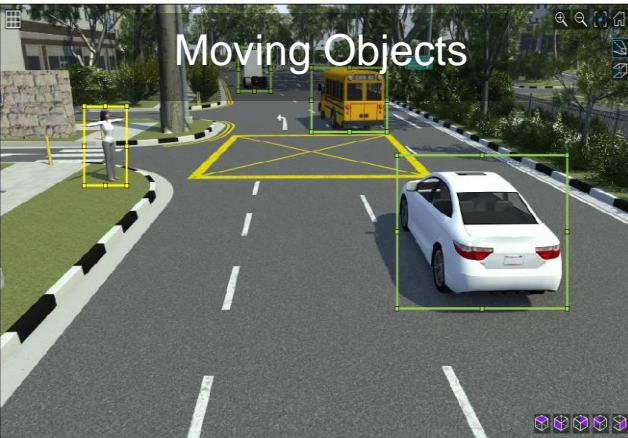
Virtual Environment



Environment Simulators mimic the real world by creating digital twin of all the assets in the real world thereby replacing many test drives on the road with virtual drives.



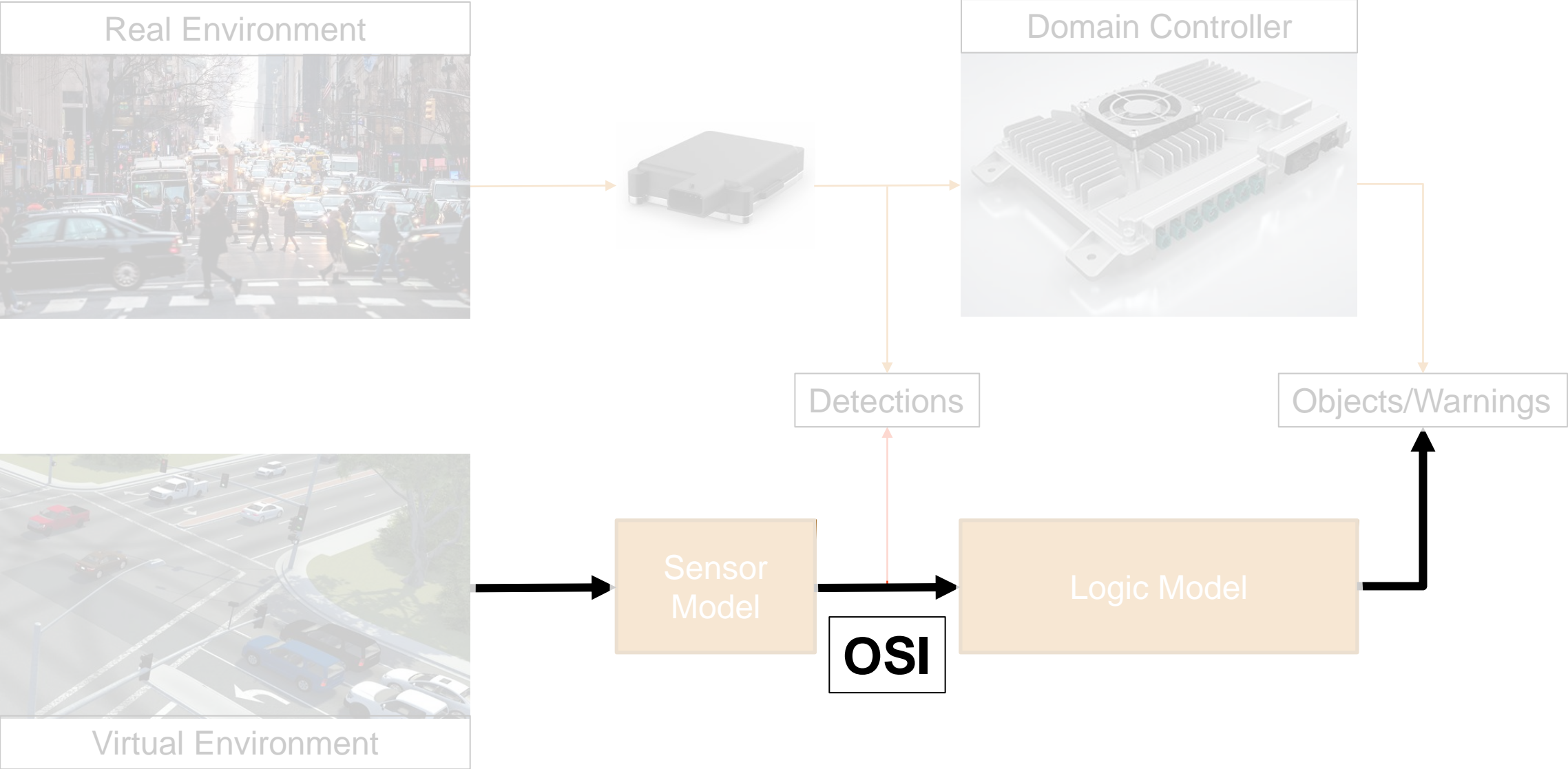
Virtual Environment



Introduction To Open Simulation Interface(OSI)

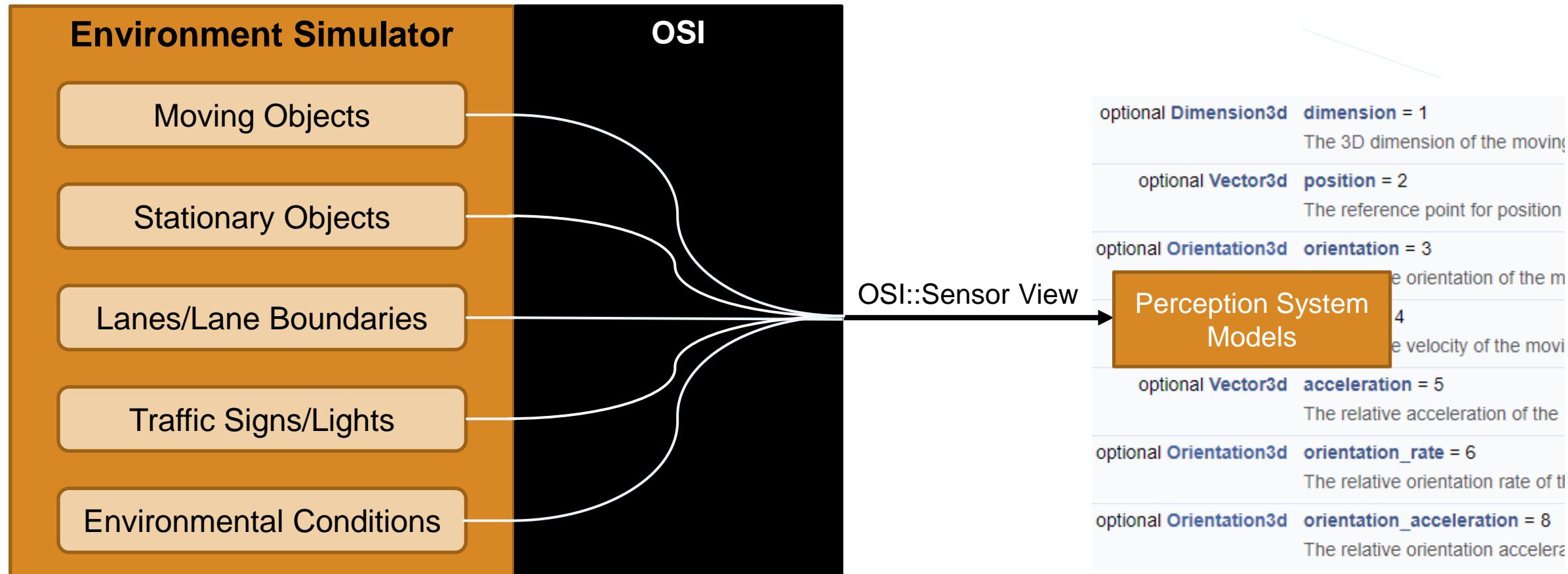


Open Simulation Interface



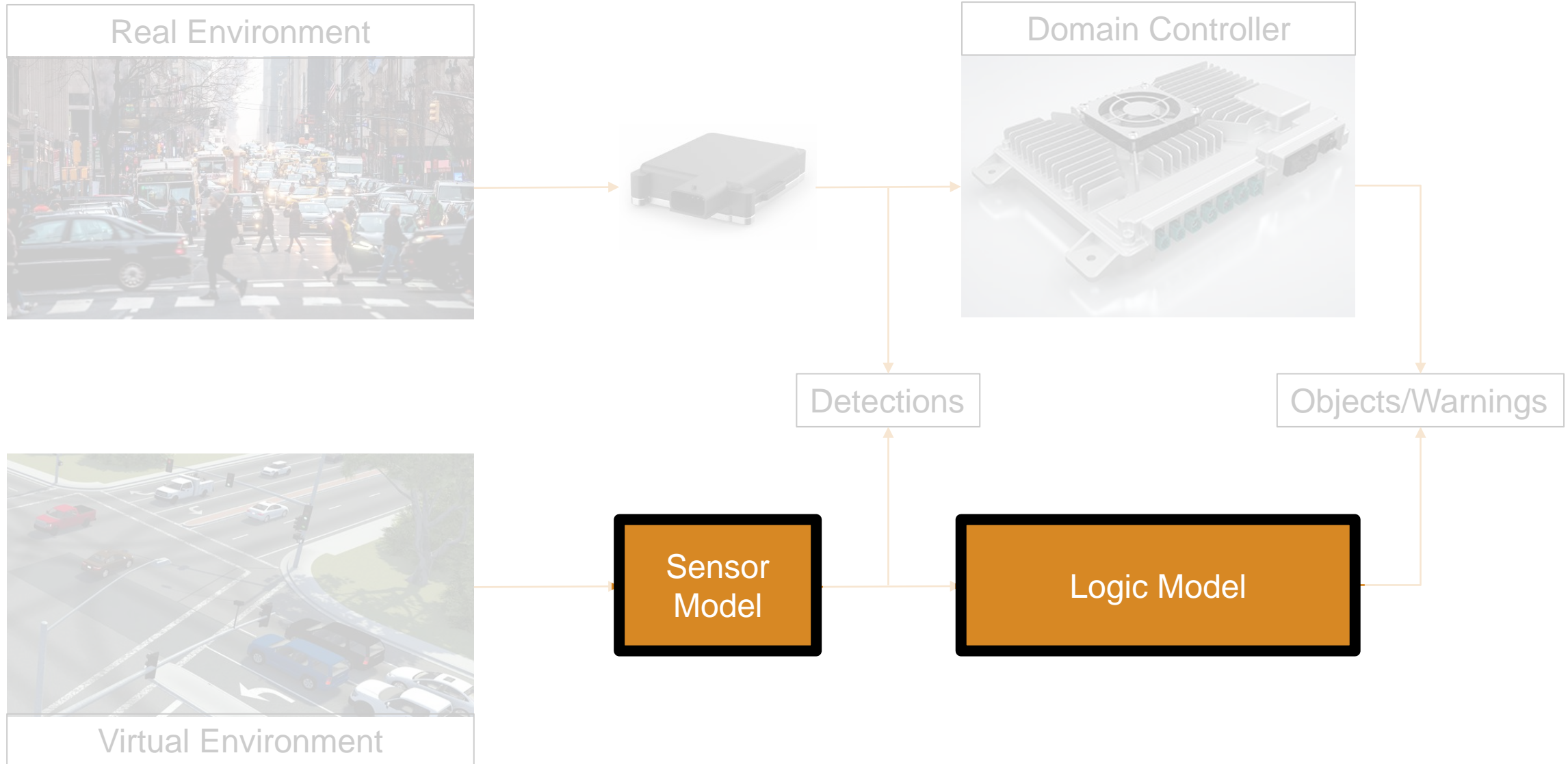
Open Simulation Interface

The Open Simulation Interface[1] (OSI) is a generic interface based on Google's protocol buffers for the environmental perception of automated driving functions in virtual scenarios[2]. All the assets from the Environment Simulators are packed into this OSI standard format. OSI supports a wide range of traffic participants from animals to trains and a variety of objects in the environment.

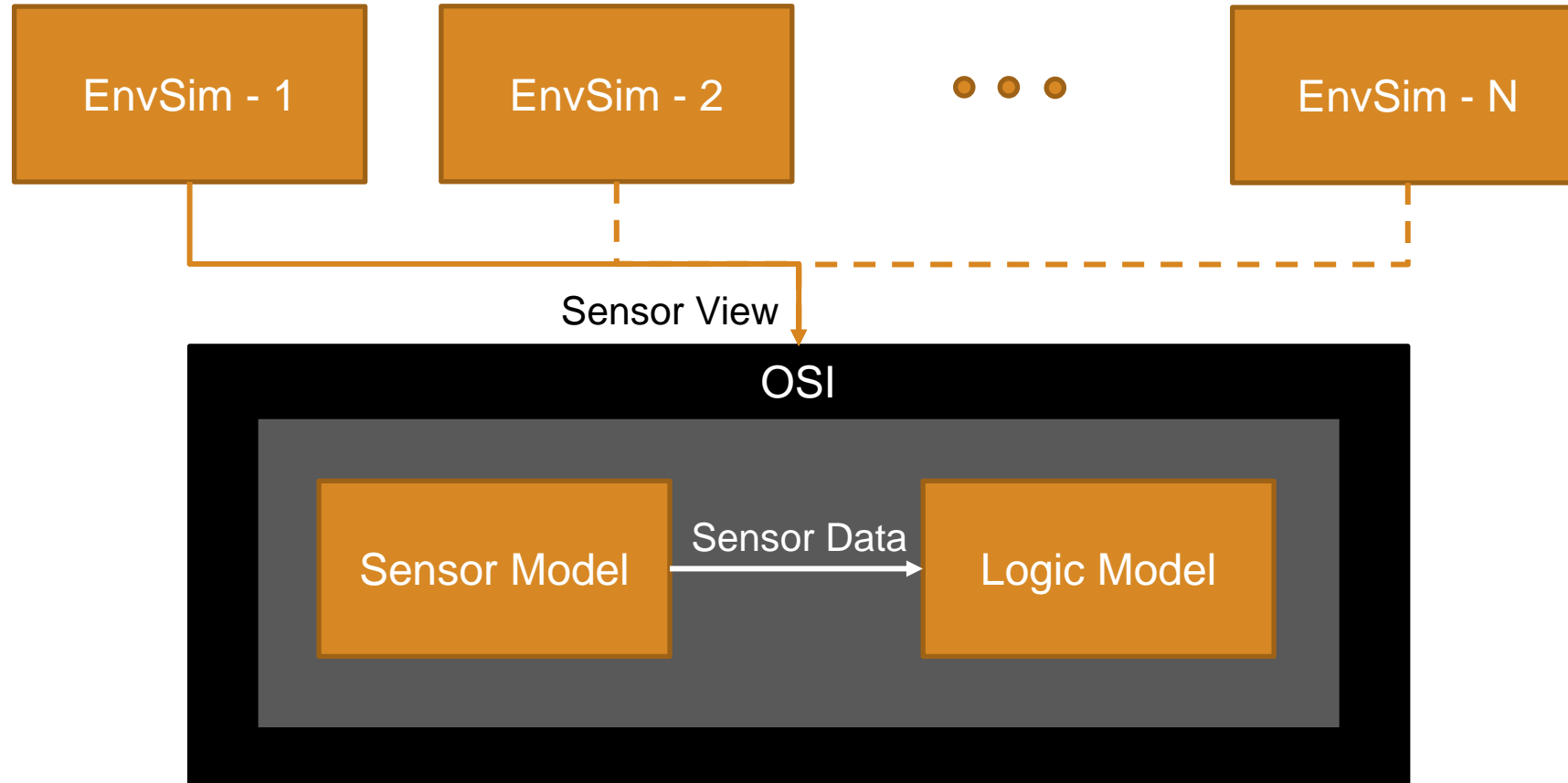


OSI In Aptiv Virtual Simulation

Virtual Simulation: OSI Based Models

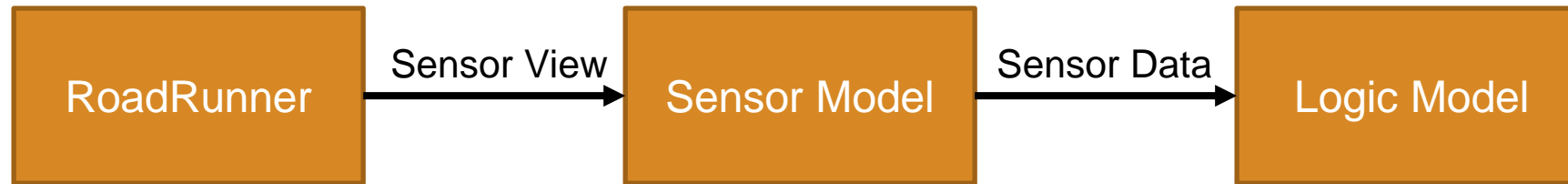


Virtual Simulation: OSI Based Models



- Perception System models, Sensor Model and Logic Model are built with OSI at its core
- Different Environment Simulators can be used with Zero change to models

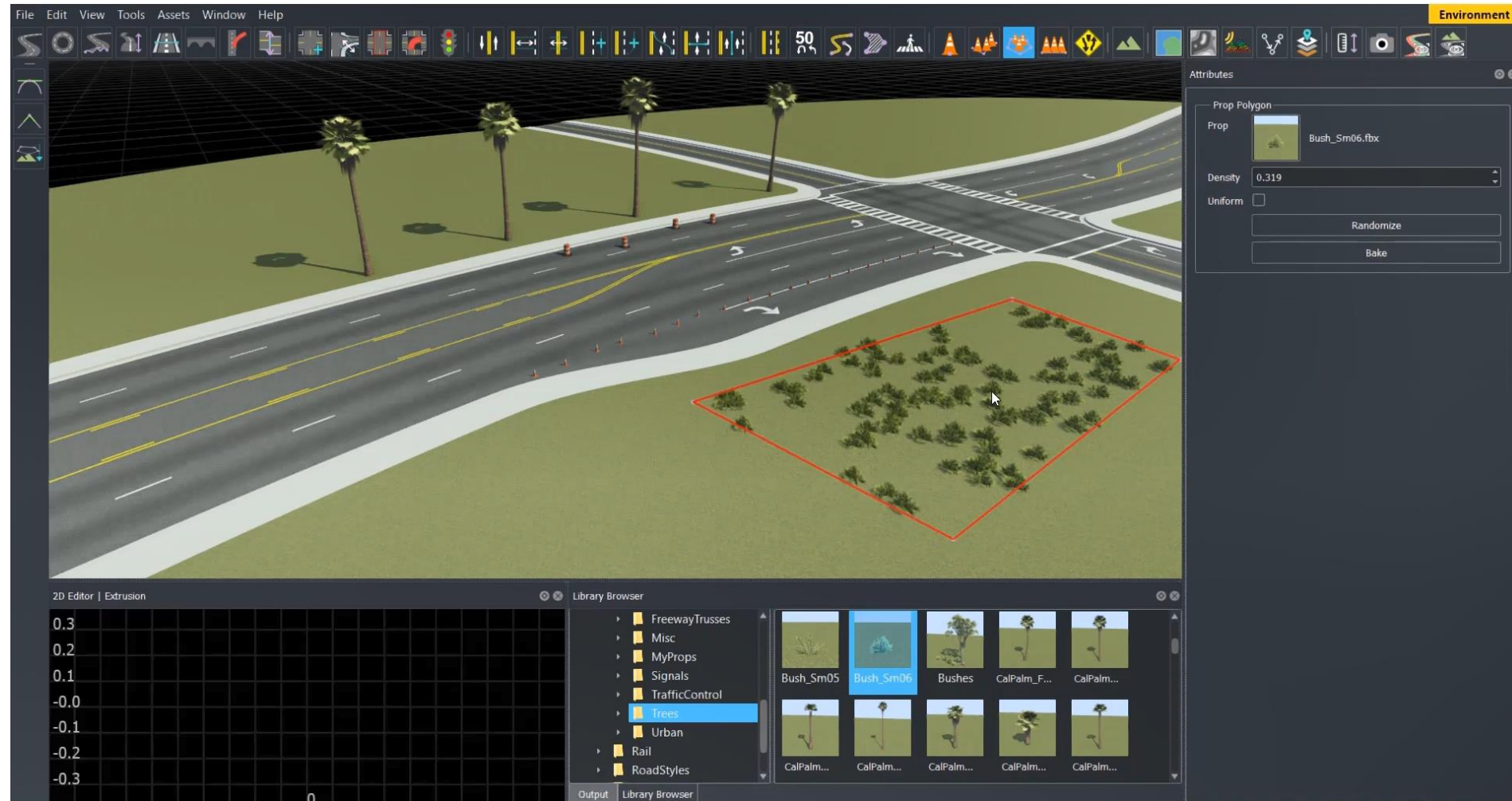
Virtual Simulation Using RoadRunner



- Developers, testers and system engineers can easily create custom scenarios using RoadRunner

Interactively design scenes with RoadRunner

- Author realistic roads and intersections
- Import/export OpenDRIVE
- Import HD maps
- Import Geographic Information System (GIS) files
- Export to common driving simulation environments



Interactively design scenarios with RoadRunner Scenario

- Add various vehicles and pedestrians
- Author trajectories
- Specify actions and logic
- Parameterize variations

SpeedBump Actions.rsscenario | 22a Project | MathWorks RoadRunner R2022a

Simulation

Simulation Controls

Pause Step Forward Stop

Time: 1.640 s

Enable Pacing to Slow Down Simulation

Slower 0.05x 1x 20x Faster

Simulation Properties

Step Size: 0.02000 s Max Time: 1000.000

Camera

Camera View: Follow

Actor: Car

Distance: 5.000

Height: 3.000

Variables

Name	
1 Hatchback_InitialSpeed	14
2 Car_NumLanesToChange	2
3 Car_LaneChangeDirection	LeftOf
4 Car_DistanceBehindSpeedBump	-17.98385

Simulation Tool

[Scenario Edit Tool](#)

RoadRunner Scenario

Updated
R2022b

Attend the Master Class to learn more on scene and scenario creation

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4:45 PM @ Sabha 2

**Scenario-Based Virtual Validation
for ADAS Features**

Munish Raj, MathWorks

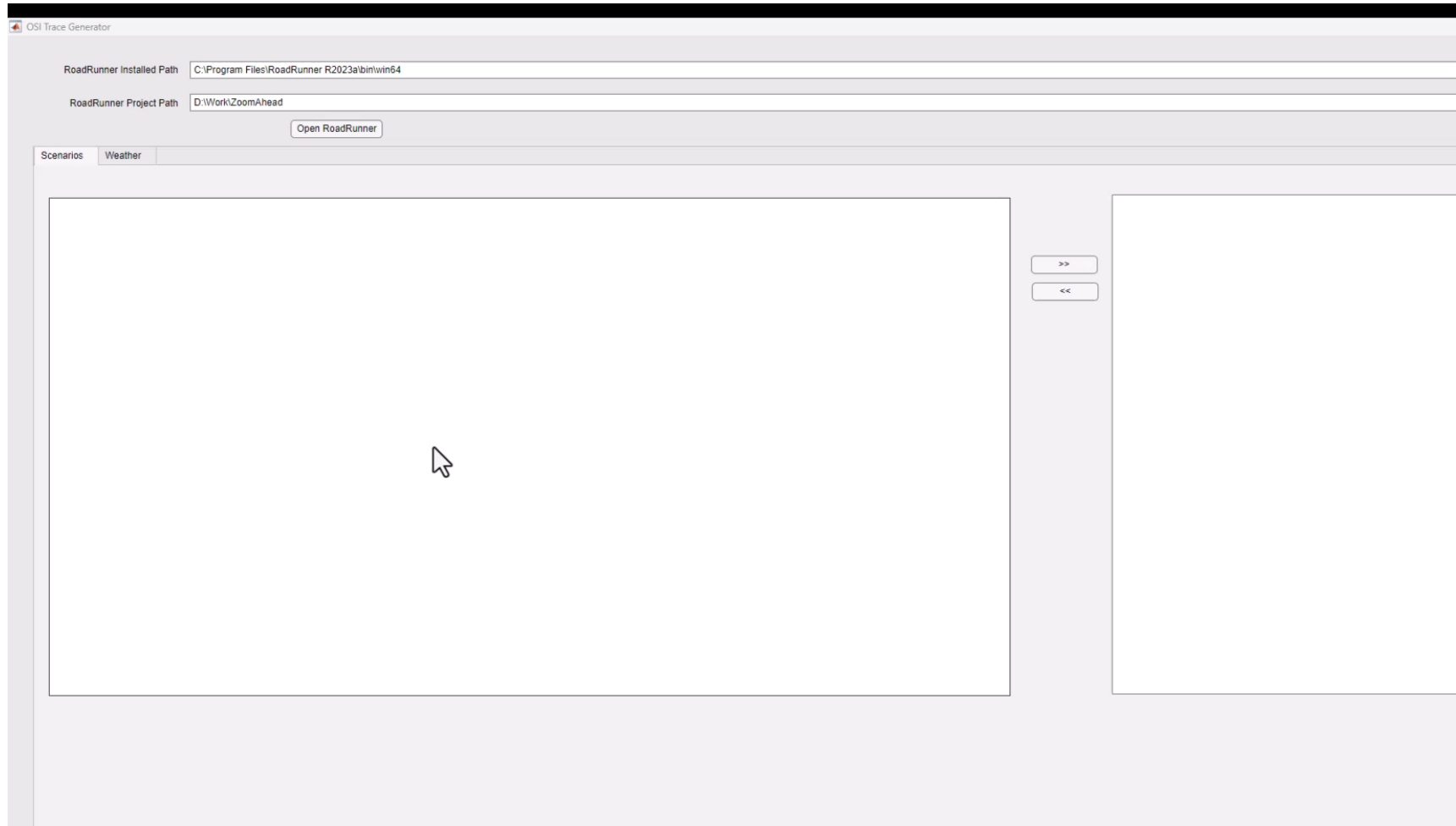


Dr Rishu Gupta, MathWorks

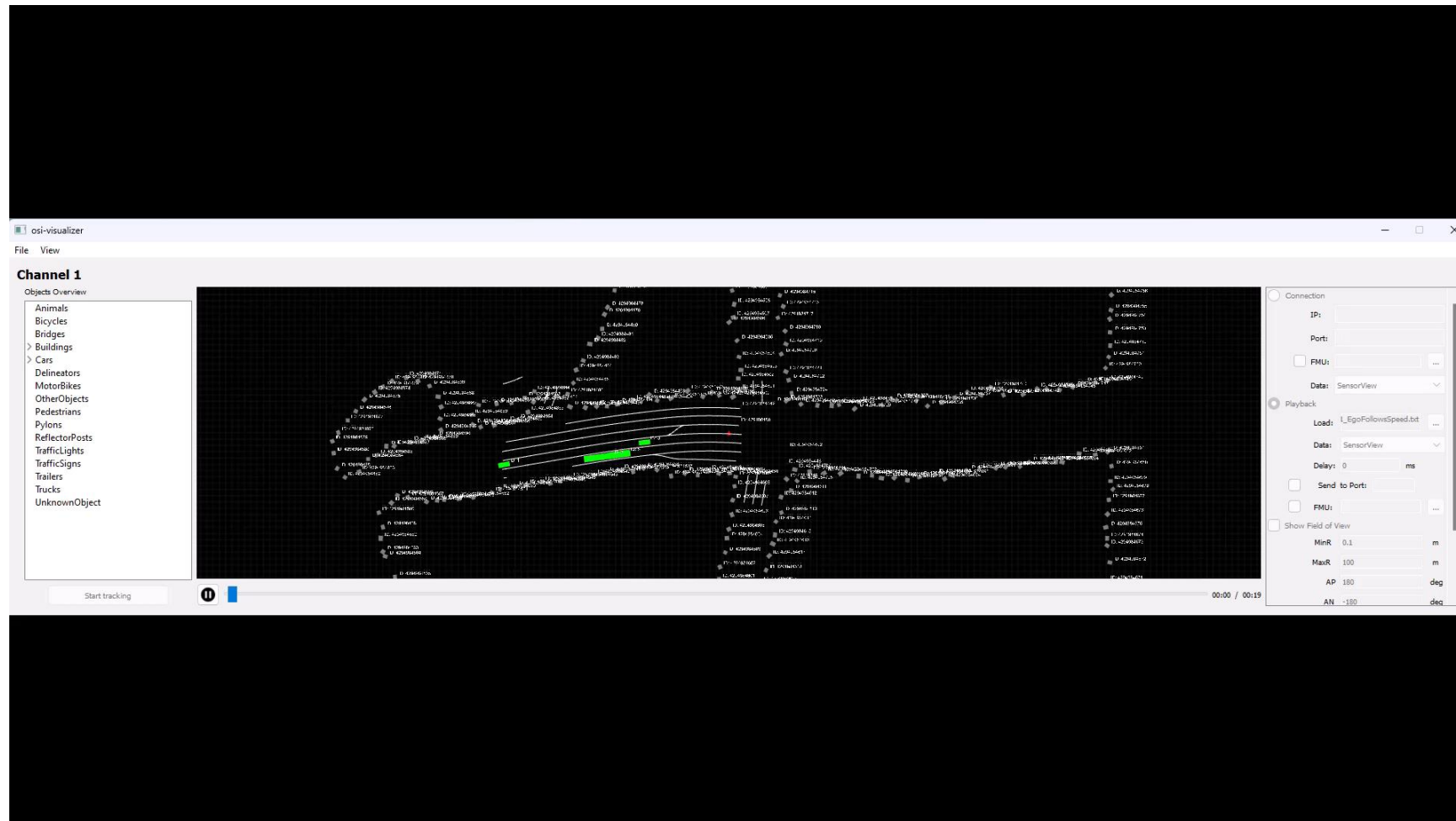


 MathWorks

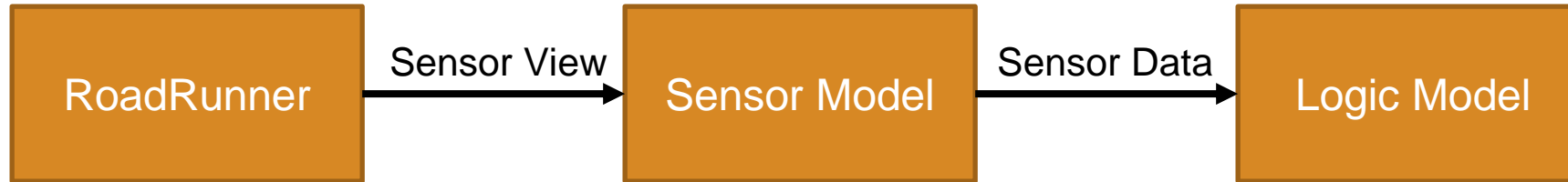
OSI Trace File Generation



OSI Visualizer



Virtual Simulation Using RoadRunner



- Developers, testers and system engineers can easily create custom scenarios using RoadRunner

OSI

Object-1

Object-2

Object-3

Object-N

Vehicle Info

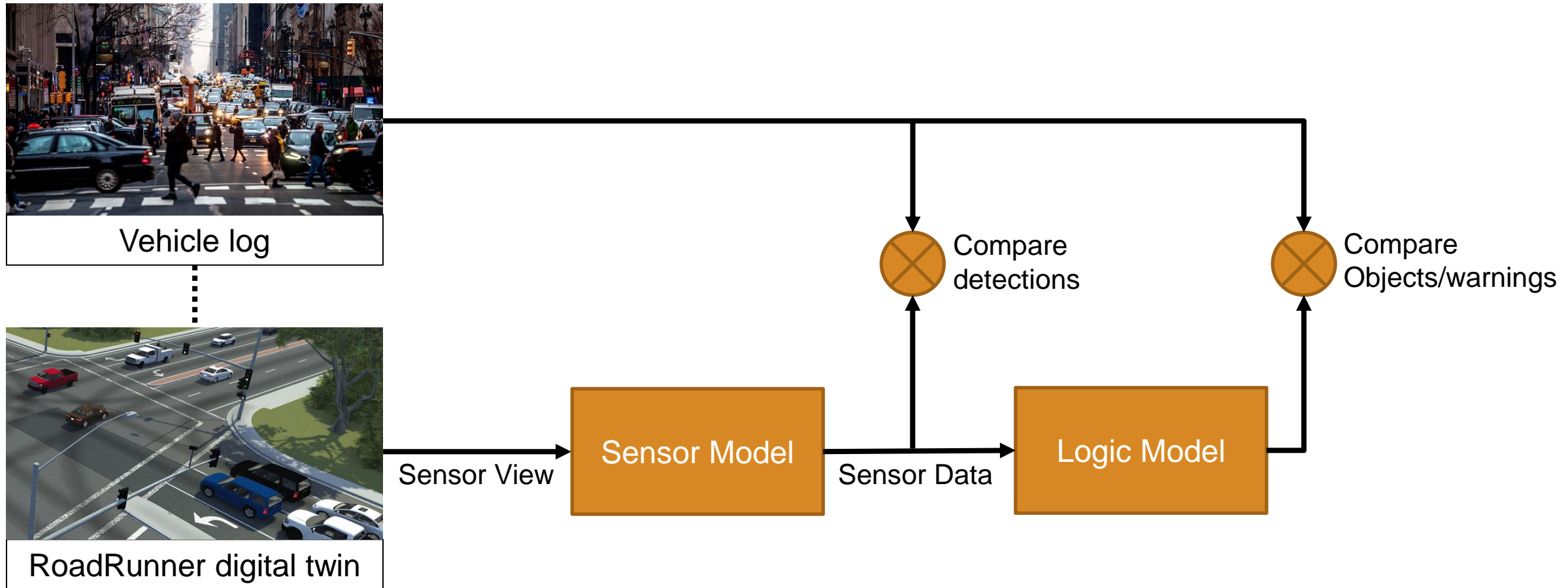
Vel (m/s): **13.89** kph: **50.00** mph: **31.07**

Yaw: **0.00** Str. Angle: **0.00** PRNDL: **D**

Feature Functions

Status	LCDA	
Overall Alert	[1] Active	[1] Active
BSW Alert	[ID: 0] [0] No Alert	[ID: 0] [0] No Alert
CWV Alert	[ID: 0] [0] No Alert	[ID: 0] [0] No Alert
CWV TTC	None	None
SLC Alert	[ID: 0] [0] No Alert	[ID: 0] [0] No Alert
SLC TTC	None	None
SLC Prob	None	None

Virtual Simulation: Validation



- Digital twin of the real-world scenario is created in RoadRunner and fed into the models via OSI. The results are then compared:
 - To validate the models
 - To check the performance of updated SW/models

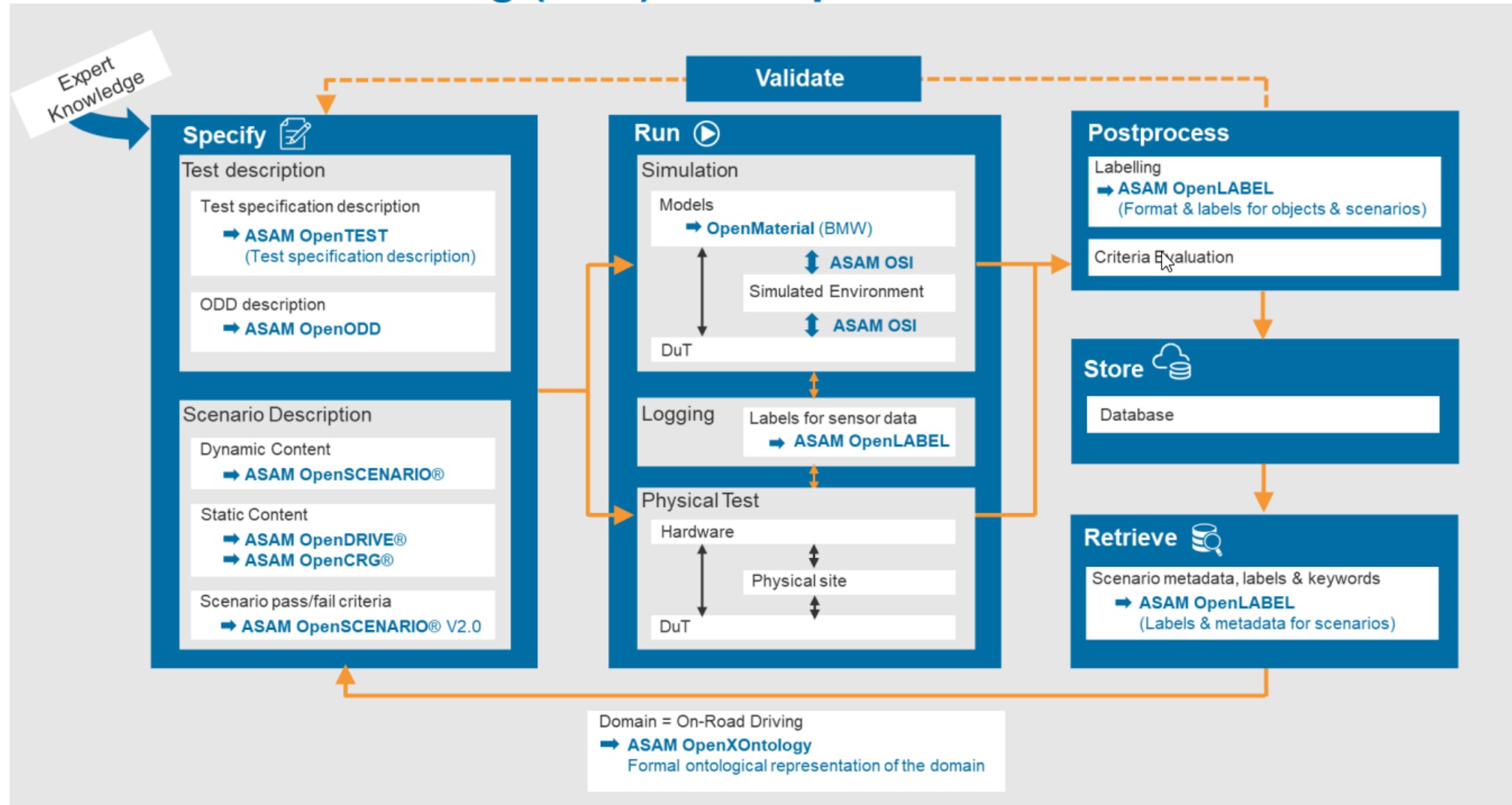
ASAM Standards



ASAM

Association for Standardization of
Automation and Measuring Systems

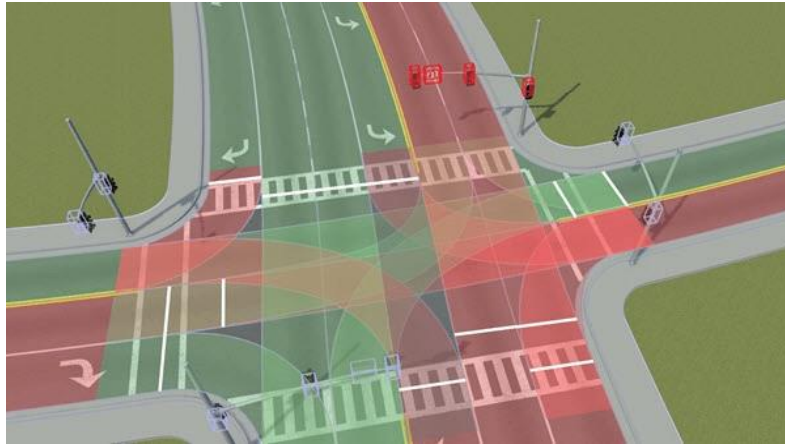
Scenario-Based Testing (SBT) with OpenX



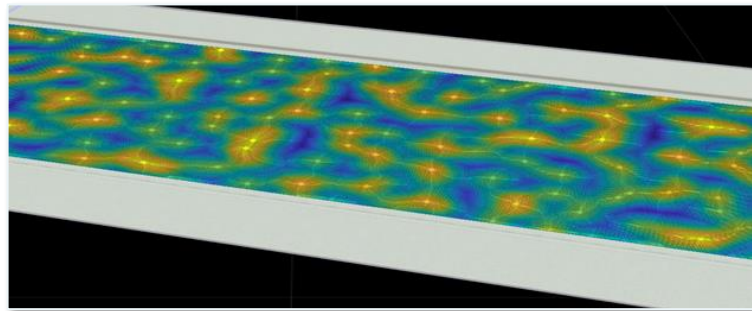
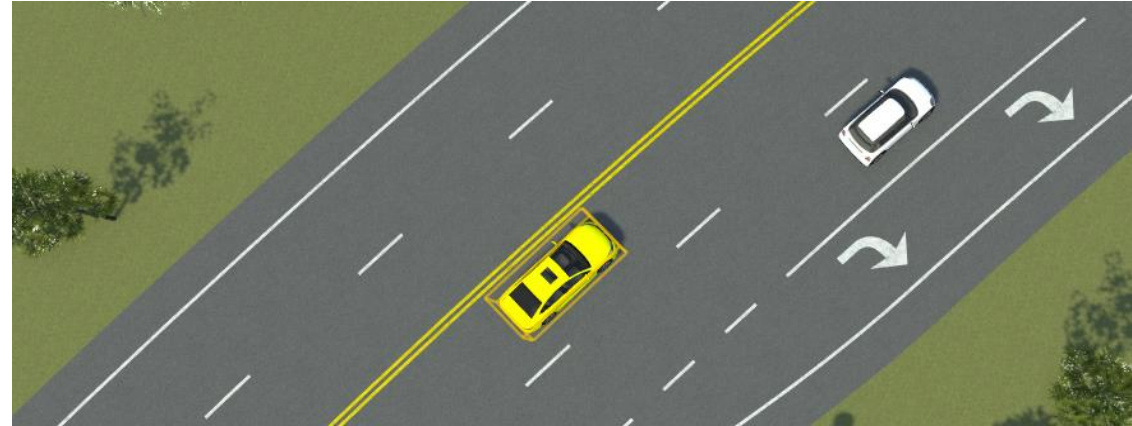
MathWorks Support for ASAM OpenX Standards



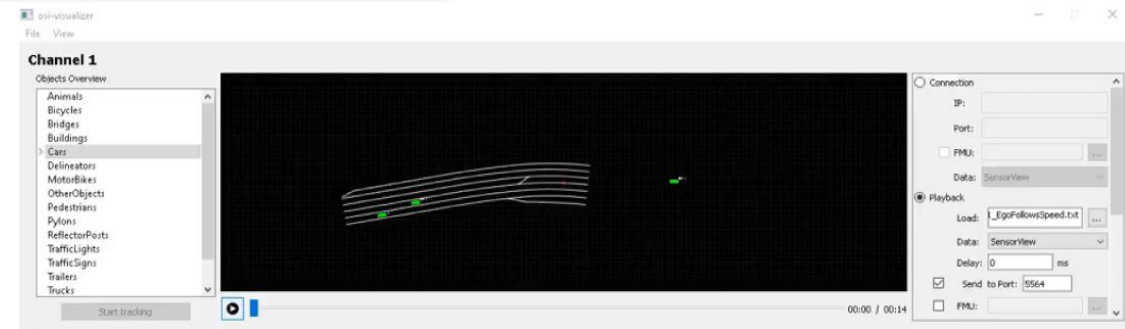
ASAM OpenDRIVE®



ASAM OpenSCENARIO®



ASAM CRG®

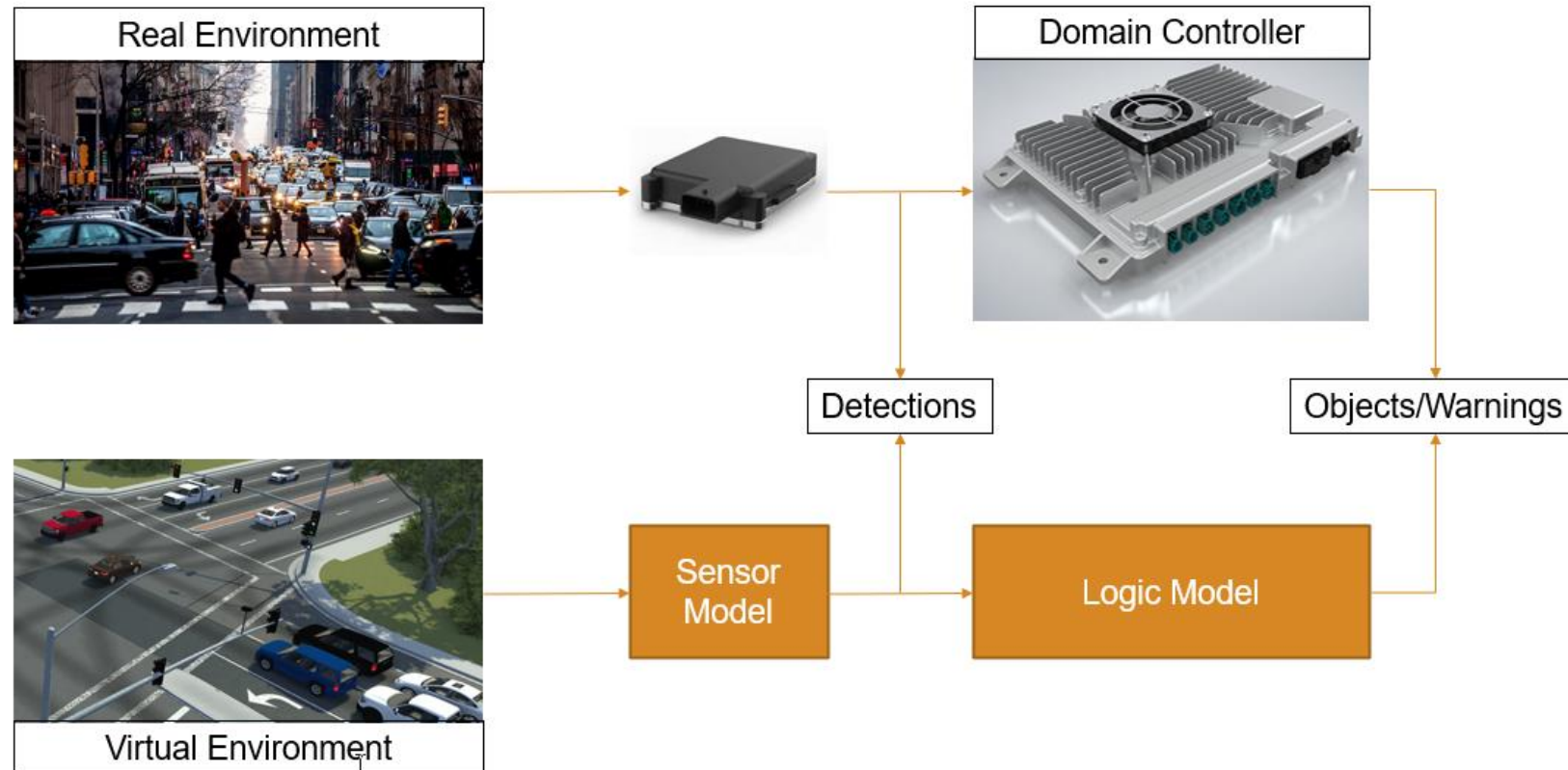


ASAM OSI®

Summary

- OSI – Standardizing the interface between simulators and models
- Platform based approach for building models
- Easy and faster scenario creation using RoadRunner
- Collaboration with MathWorks has been very fruitful in integrating OSI to RoadRunner.

Virtual Simulation



References

- [1] Hanke, T., Hirsenkorn, N., van-Driesten, C., Garcia-Ramos, P., Schiementz, M., Schneider, S. & Biebl, E. (2017, February 03). A generic interface for the environment perception of automated driving functions in virtual scenarios. Retrieved January 25, 2020, from <https://www.hot.ei.tum.de/forschung/automotive-veroeffentlichungen/>
- [2] <https://github.com/OpenSimulationInterface/open-simulation-interface>
- [3] <https://github.com/OpenSimulationInterface/osi-visualizer>

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Thank you

