

Home Appliance Controls Development using Model Based Design

Presented By : Priti Madurwar, Pranoti Joshi

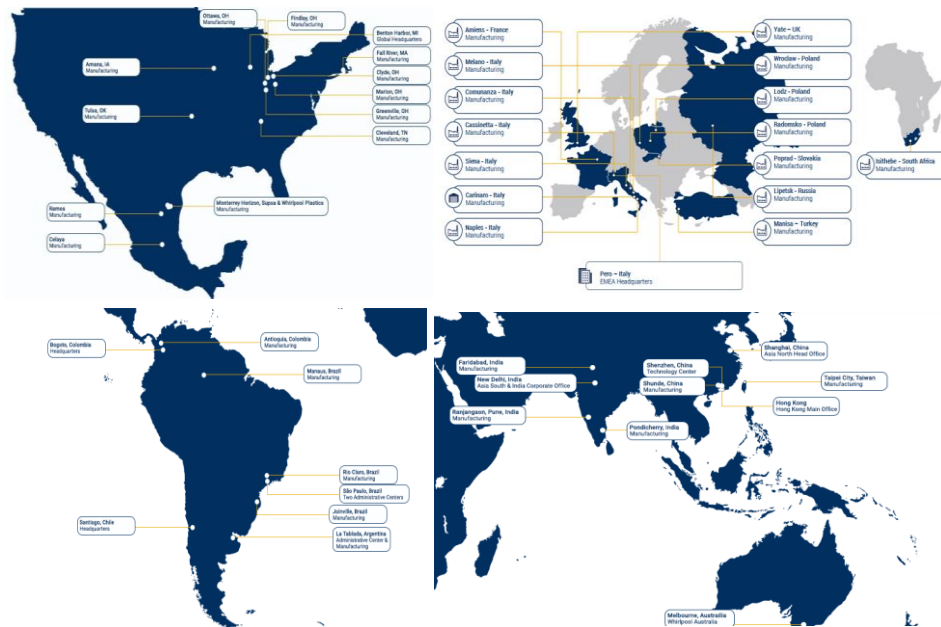
A blue arrow-shaped graphic pointing to the right, containing the text "MATLAB EXPO 2019" and "PUNE" in white, bold, sans-serif font. The arrow's tail is decorated with a pattern of small, multi-colored squares (blue, green, white) that fade out towards the tip.

MATLAB EXPO 2019
PUNE

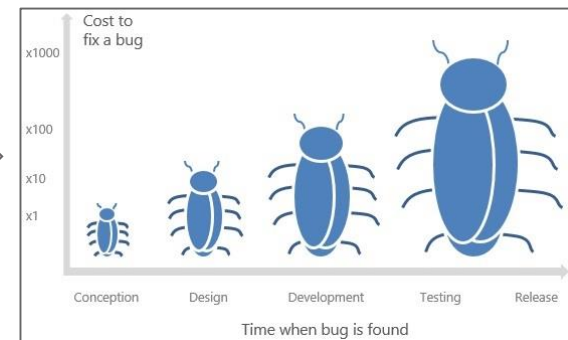
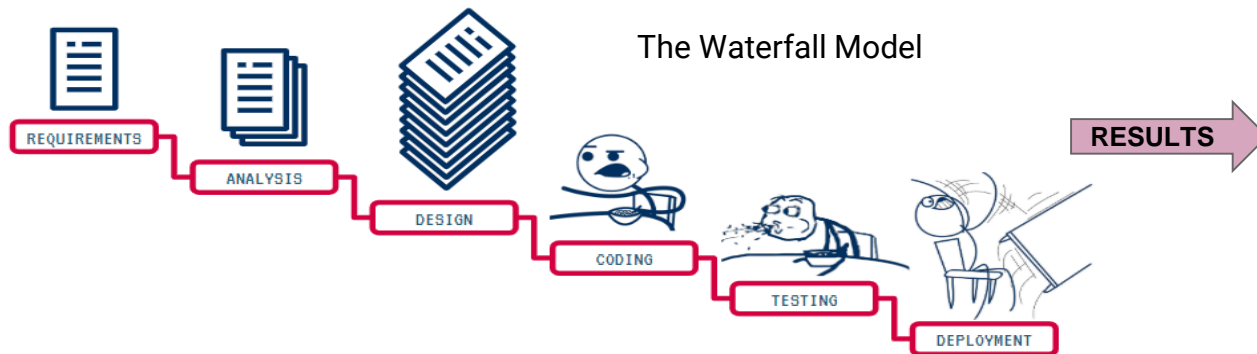
- **About Whirlpool**
- **Model Based Development Process in Whirlpool**
- **Case Study : Universal Motor Controls Development**
- **Organisational Benefits through MBD**

About Whirlpool

- World's leading major Home Appliance company
- Founded over 100 years ago
- ~\$21 billion in revenue in 2018
- 92,000 employees and 70 manufacturing and technology research centers
- 1 in 3 employees volunteer for taking care of our neighborhoods and the planet



Limitations of Traditional Software Development Process



Poor Requirements Management

ID	Content
23168	ANTI FOAM MONITOR
23168	The foam detection will be performed by monitor the monitor will have a good monitor (I will not do the upper monitor)
23168	The monitor will access to the data regarding the water quantity through the foam level monitor (the monitor will be used to check if the required amount is check is empty.)
23168	The monitor will interact with the motor to remove the foam level above through the motor pool
23168	The monitor must have a method that allow it to be enabled and disabled

```

23168 // Public Function Prototype used for the
23168 // private void DetectFoamLevel() {
23168 //     try {
23168 //         if (mFoamLevel > mFoamLevel) {
23168 //             mFoamLevel = mFoamLevel;
23168 //         } else {
23168 //             mFoamLevel = mFoamLevel;
23168 //         }
23168 //     } catch (Exception e) {
23168 //         mFoamLevel = mFoamLevel;
23168 //     }
23168 // }
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23168 //         }
23168 //     } catch (Exception e) {
23168 //         mFoamLevel = mFoamLevel;
23168 //     }
23168 // }
    
```

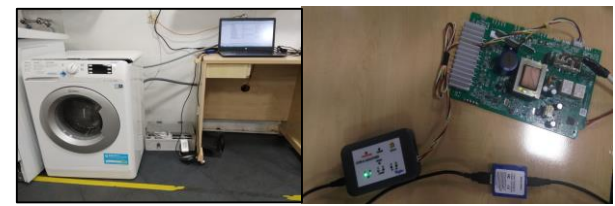
- Missing linkage between requirement and software code.
- Unfreeze requirements

Manual Code Implementation



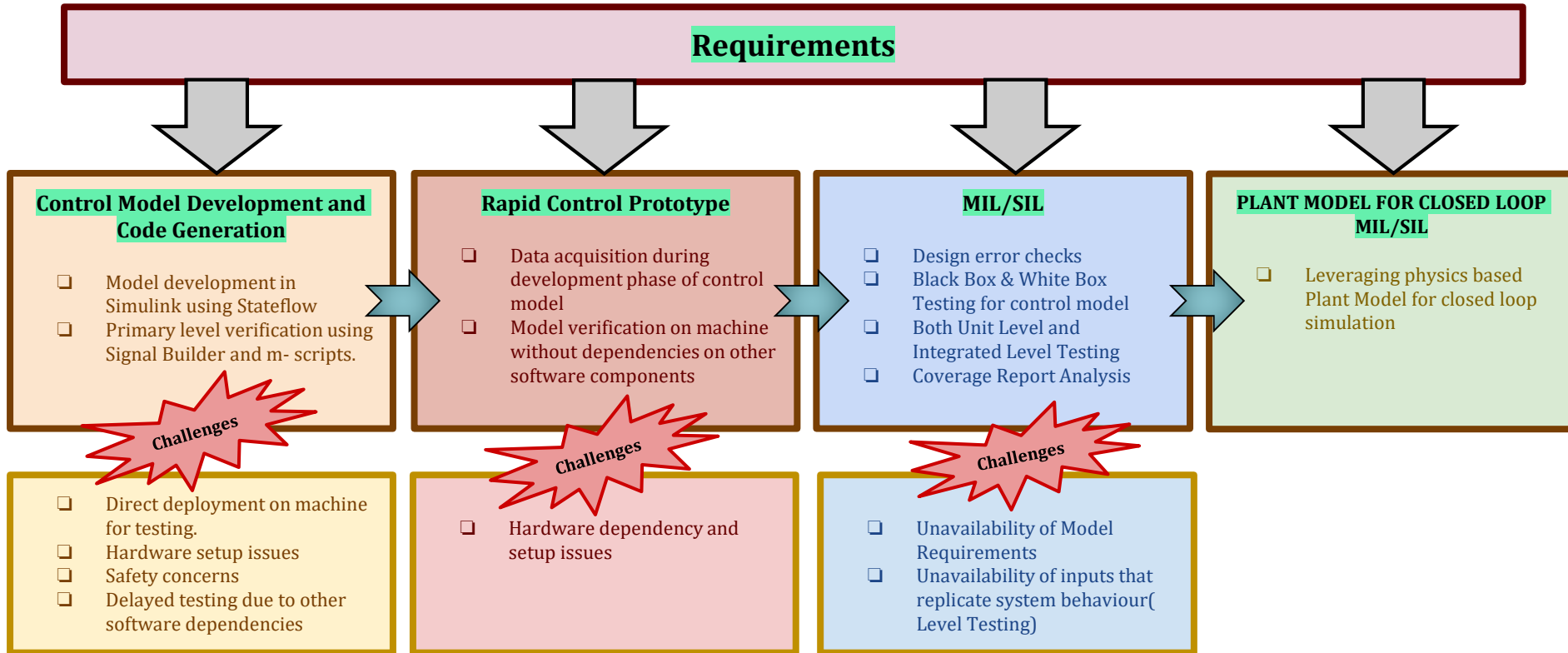
- Squeezed timelines.
- Software Integration with cross regional teams in workforce.
- Less readability , difficult debugging
- Variation in implementation method from developer to developer.

Hardware requirement for Verification

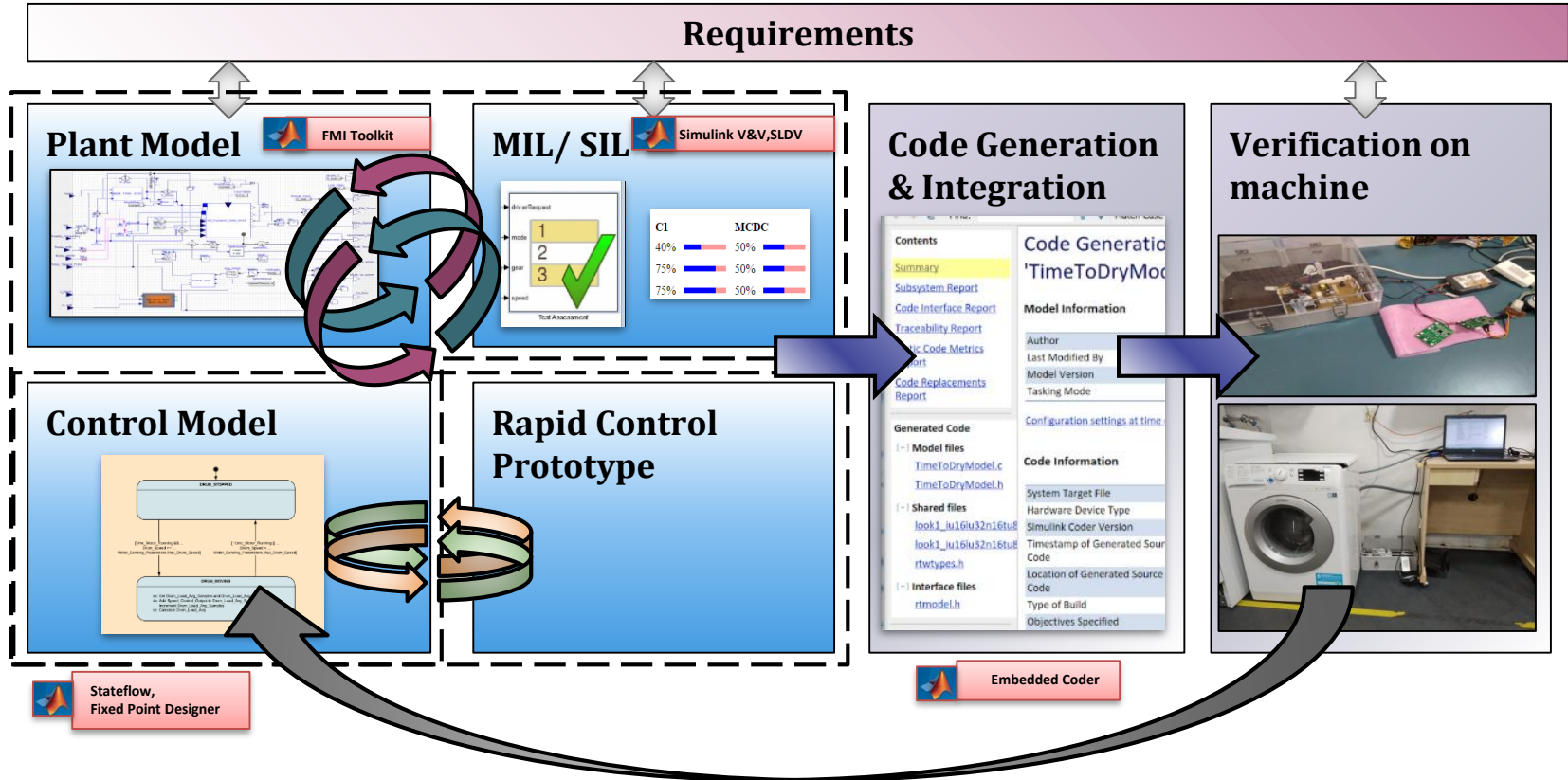


- Setup & Maintenance Cost Involved.
- Difficult setup replication.
- Hardware availability.
- Safety of Tester.

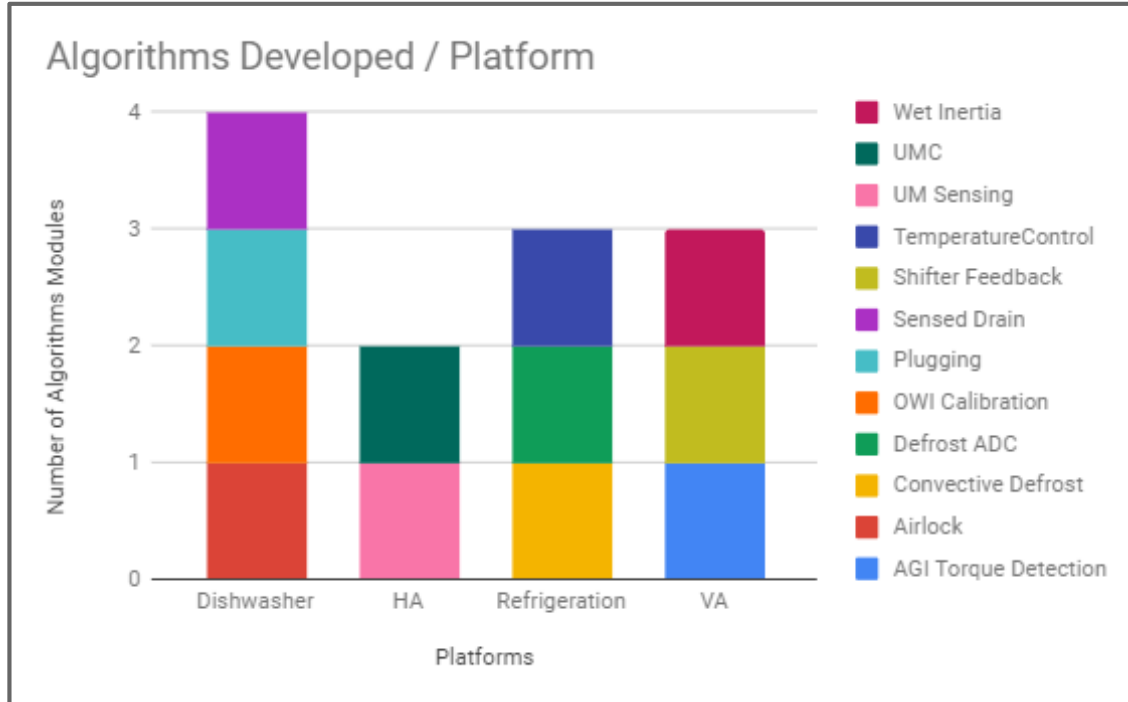
MBD process in Whirlpool...Few years Ago



Current MBD Workflow in Whirlpool

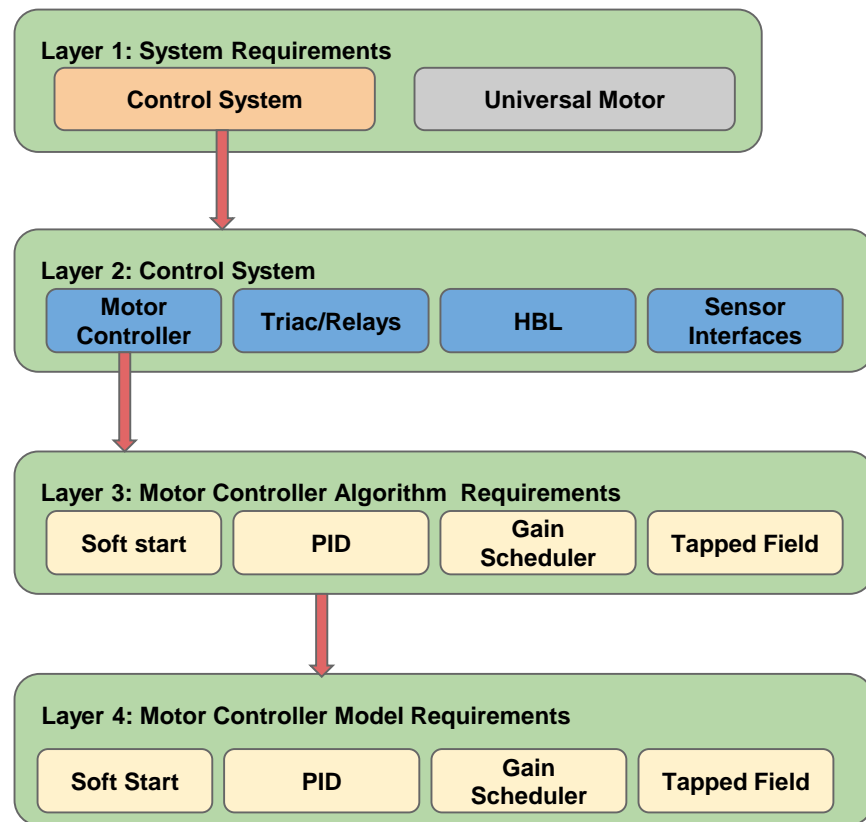


Summary of MBD algorithm in different whirlpool products



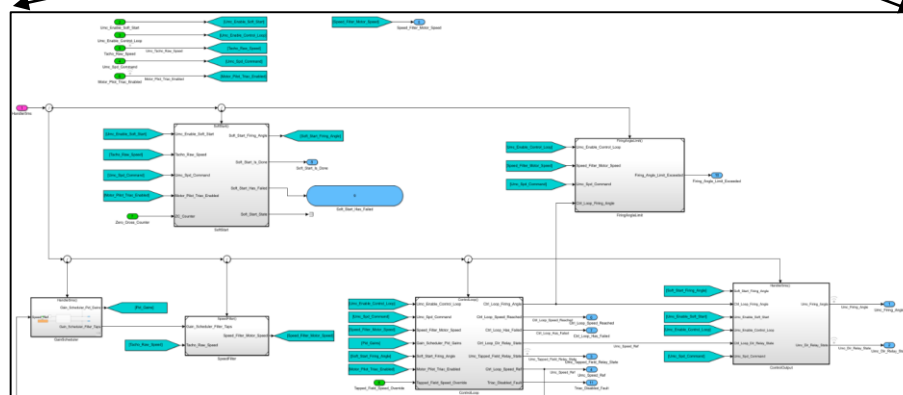
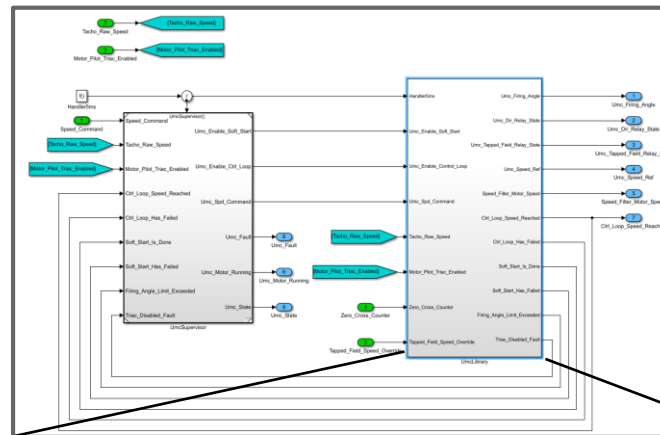
Universal Motor Controls Development

- Requirements breakdown
- Class Diagrams for Controller using SysML
- System Engineering Support for development of Universal Motor Plant Model
- Verification at Module level as well as integrated level.



Algorithm Modeling Using Stateflow & Simulink

- Algorithm requirements have been implemented as a Simulink® model
 - Floating/Fixed point, Fixed step size
 - Use most convenient tools (Simulink, Stateflow, MATLAB code blocks)
 - Use referenced model
 - Use of Data Dictionaries
 - Capturing Model Metrics
 - Traceability

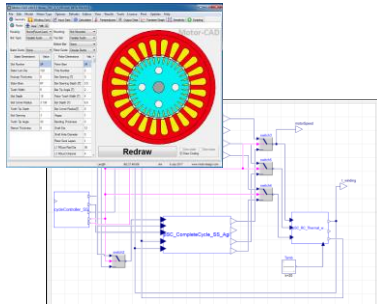


*Stateflow, Matlab Functions,
Simulink Blocks, Fixed Point Designer*



Universal Motor and Washer Dynamics Plant Model

Plant Model Development

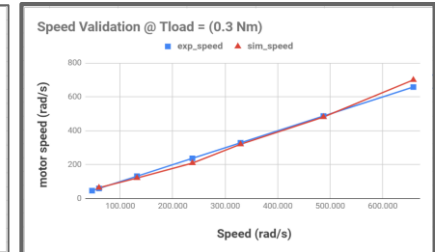
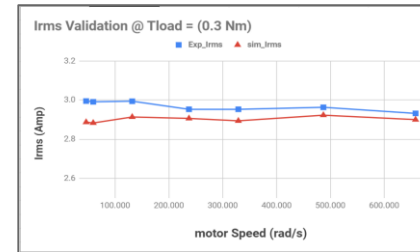


```

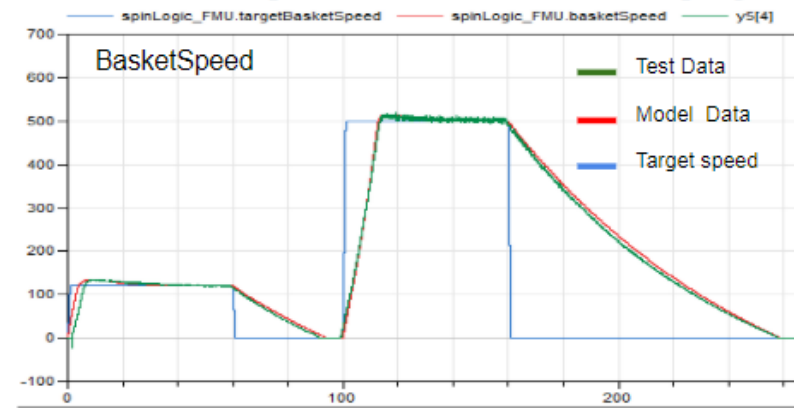
parameter Real m_t = 12.176; //tub mass 12.176
parameter Real m_d = 15.79; //drum mass 9.52
parameter Real m_u = 0; //unbalance mass
parameter Real m_b1 = 0; //mass of water ring1
parameter Real m_b2 = 0; //mass of water ring2
parameter Real e = 0.25349; //unbalance radius
parameter Real d = 0.295; //balance ring radius
parameter Real I_zt = 0.54; //tub inertia
parameter Real I_zd = 0.95; //drum inertia 0.69826
parameter Real K=2600; //spring Co-efficient (N/m) 3300
parameter Real Cd=200; //Damping Coefficient 28
parameter Real T_f=0.6; //Friction torque 1
parameter Real C_b1=0.1; //viscous drag co-efficient of water ring1
parameter Real C_b2=0.1; //viscous drag co-efficient of water ring2
parameter Real D_r=0.016; //viscous drag co-efficient of machine shaft 0.001
    
```

- Model Based System Engineering team support for Plant Model Development
- Use of Dymola/Modelica environment
- Calibration of Plant Parameters with Real Time Test Data

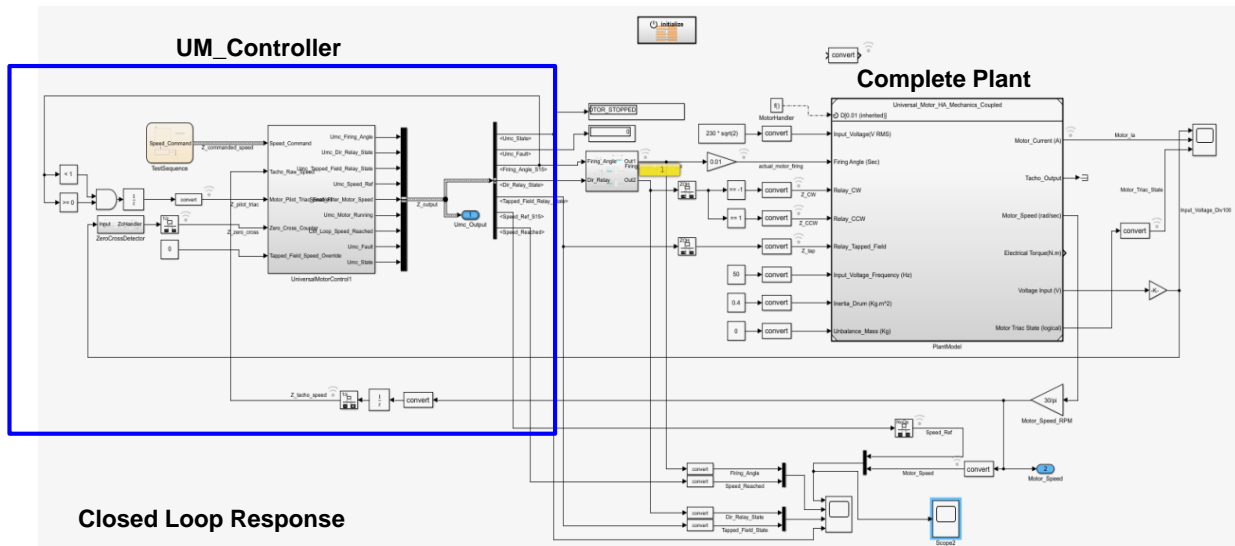
Open Loop Validation



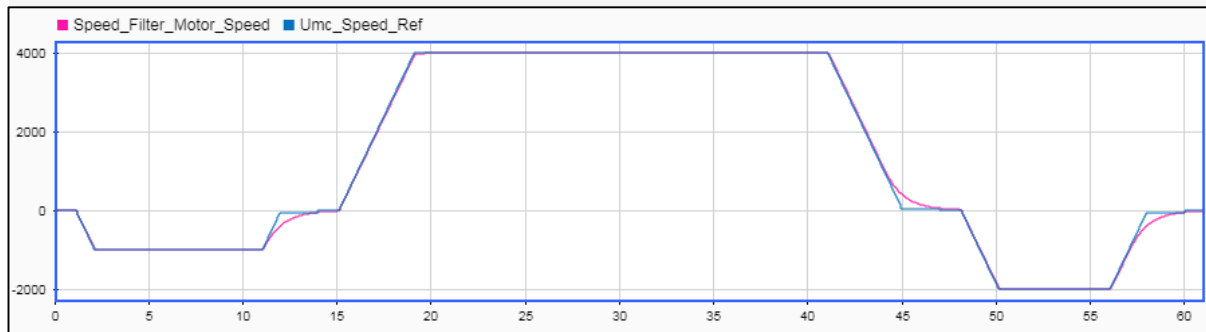
Closed Loop Validation with Basic Control



Integration of Control Model and Plant Model



Closed Loop Response

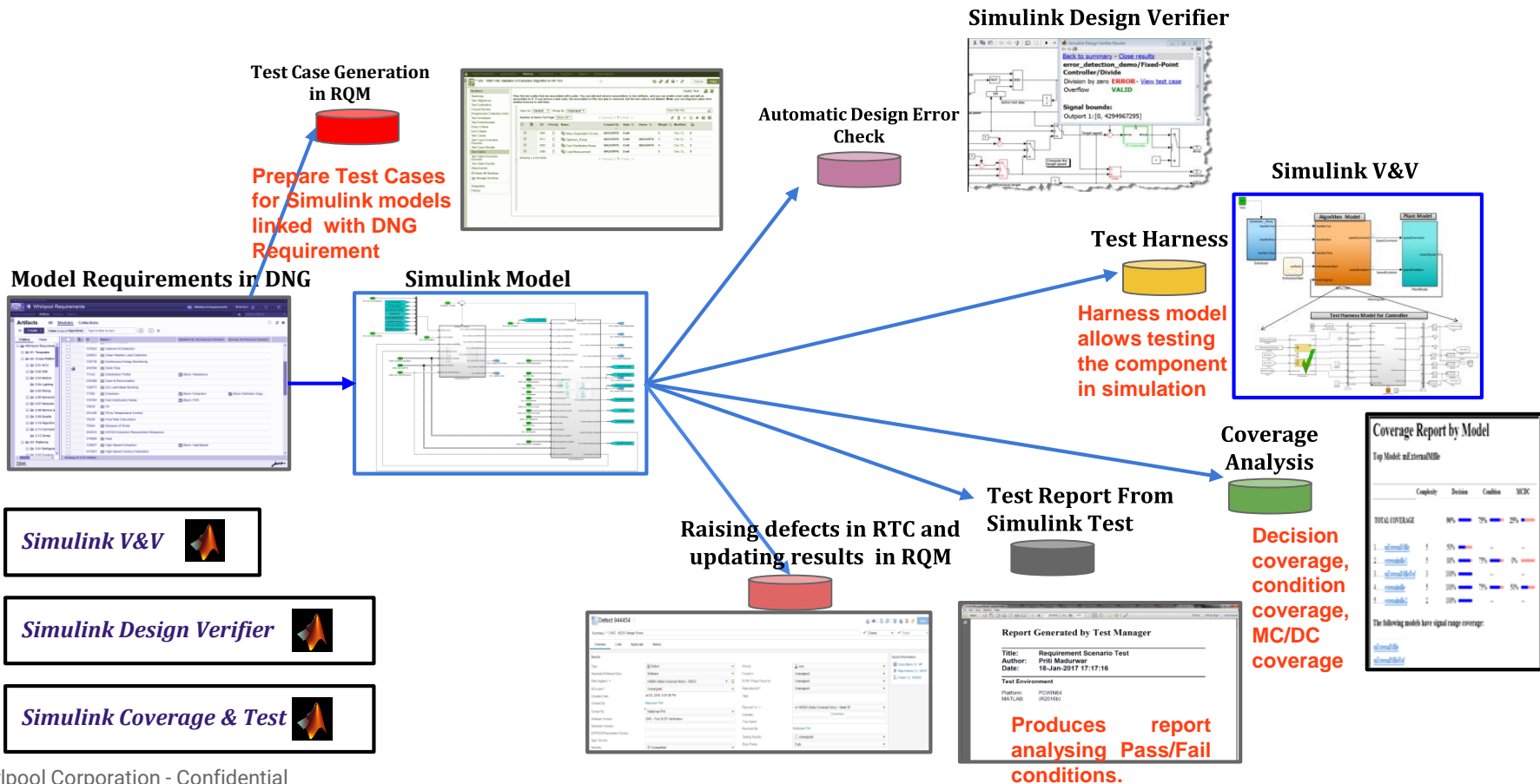


- Use of Functional MockUp units for leveraging Dymola Plant Models in Simulink
- Provides Capability to find robustness of the logic at system level.
- Allows to perform System Level verification

*Simulink PSP Toolbox till 2016
Inbuilt Simulink FMI kit feature
2017 onwards*



Verification and Validation



Coverage Report by Model

Top Model: mExternalMtlb

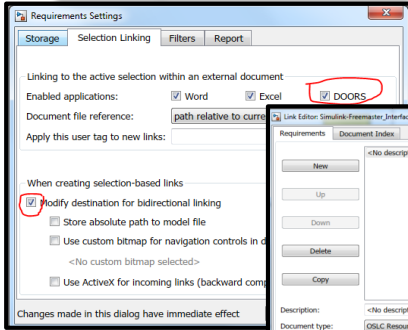
	Complexity	Decisions	Conditions	MC/DC
TOTAL COVERAGE	8%	7%	2%	0%
1. <i>mExternalMtlb</i>	5	5%	—	—
2. <i>mExternalMtlb</i>	5	0%	7%	0%
3. <i>mExternalMtlb</i>	3	33%	—	—
4. <i>mExternalMtlb</i>	5	0%	7%	0%
5. <i>mExternalMtlb</i>	2	33%	—	—

The following models have signal range coverage:

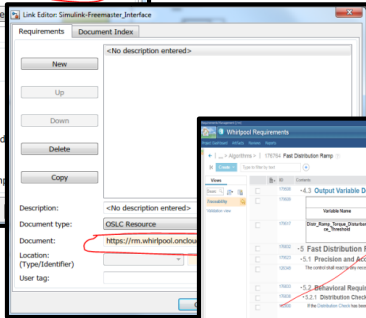
- mExternalMtlb*
- mExternalMtlb*

Requirement Linking from Simulink to DNG

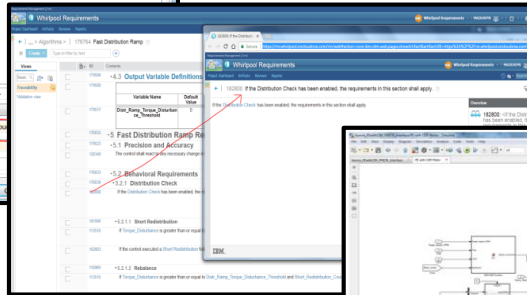
Configure Requirement Settings



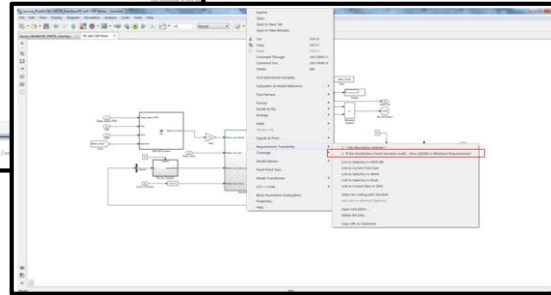
Select Project Area from DNG



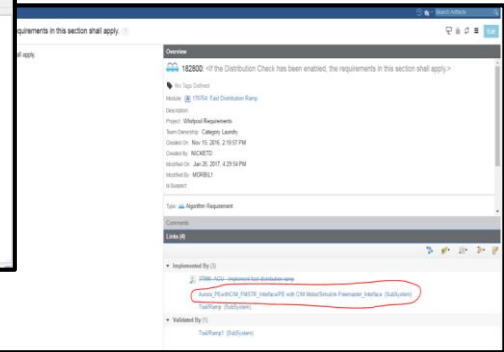
Selecting Requirement from DNG



DNG Link of requirement in Simulink



Simulink Implemented link in DNG



Simulink Requirement Toolbox



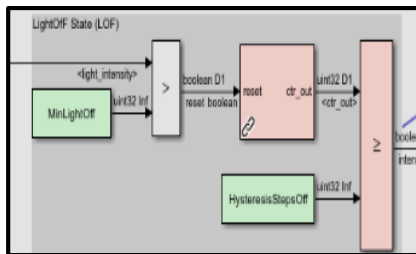
Application of Simulink V&V & Design Verifier

Simulink Validation & Verification

1. Cumulative coverage results on multiple tests

Summary					
Model Hierarchy Complexity					
	Test 1	Decision	Condition	MCDC	Execution
1. ...	14	100%	100%	100%	100%
2. ...	8	100%	100%	NA	100%
3. ...	NA	NA	100%	NA	100%
4. ...	NA	NA	100%	NA	100%
5. ...	3	100%	100%	NA	100%
6. ...	NA	NA	NA	NA	100%
7. ...	2	100%	NA	NA	100%
8. ...	2	100%	NA	NA	100%
9. ...	25	100%	100%	100%	100%
10. ...	24	100%	100%	100%	100%
11. ...	18	100%	100%	100%	NA
12. ...	1	100%	NA	NA	100%
13. ...	1	100%	NA	NA	100%

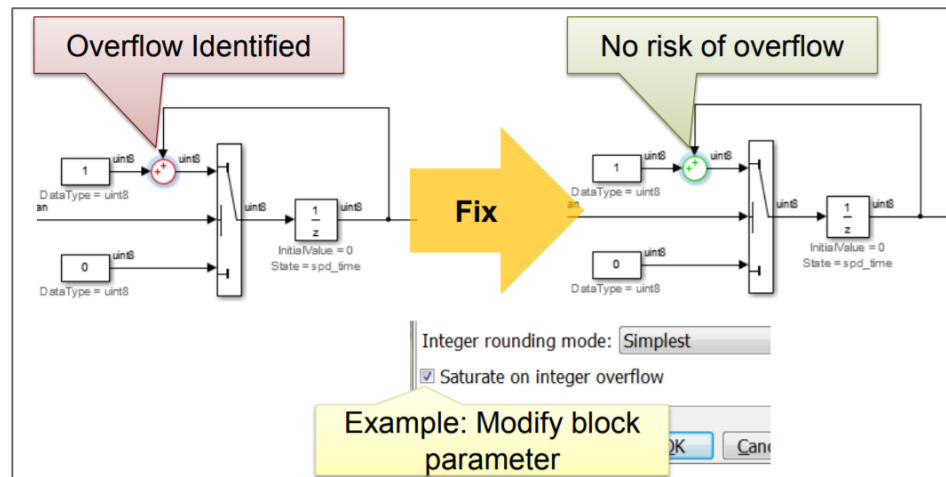
2. Identified missing coverage



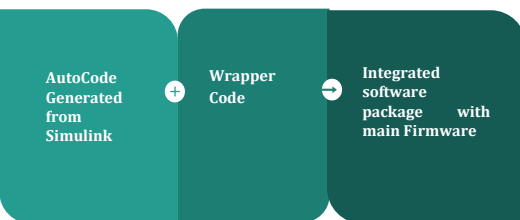
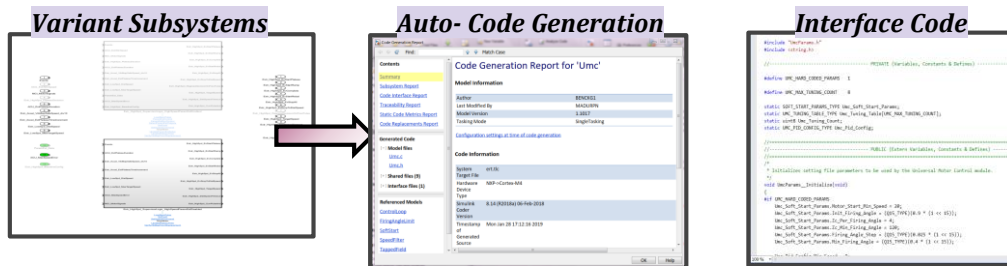
3. Traceability between DOORS requirements and Model

Simulink Design Verifier


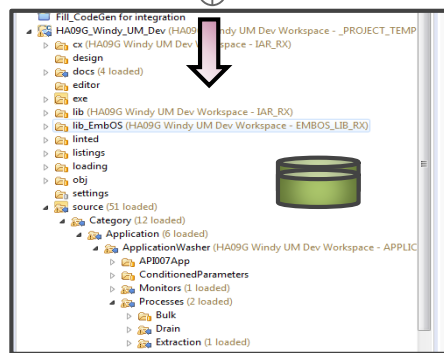
Check for risks of software design errors prior to implementation
 Integer overflow, division by zero, range violations, dead logic



Code Generation and Integration



Toolboxes Used:
 Stateflow,
 Embedded Coder,
 Fixed Point Designer,
 Matlab coder,
 Simulink Coder

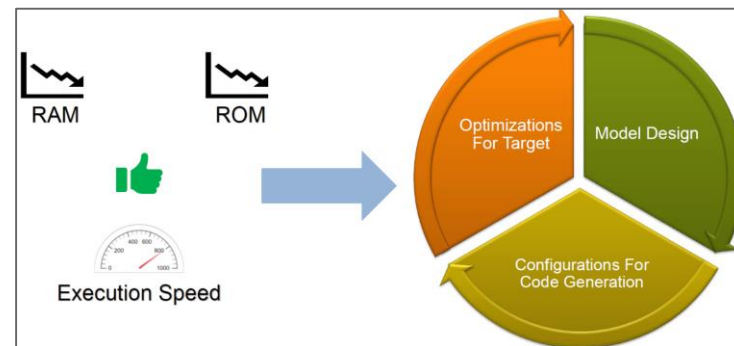
Delivery of complete package to the stream

Achieving Optimized Code: (reference MATLAB EXPO 2018)

- Use of Model Advisor to apply and establish best Modeling practices
 - MAAB/MISRA C, ISO/IEC Standards etc
 - Simulink and Stateflow guidelines

Model Advisor Guidelines

- > Modeling Standards for DO-178C/DO-331
- > Modeling Standards for EN 50128
- > Modeling Standards for IEC 61508
- > Modeling Standards for IEC 62304
- > Modeling Standards for ISO 26262
- > Modeling Standards for MAAB
- > Modeling Standards for JMAAB
- > Modeling Standards for MISRA C:2012



Advantages of Model Based Design

- ❑ Consistent design flow from conception to implementation using same language
- ❑ Detecting errors in early stages of Software Development
- ❑ Easy to deploy code in different projects by managing variant subsystems.
- ❑ Easy to handle change requests without impact on timelines.
- ❑ Very few defects in released softwares
- ❑ Early observation for unexpected emergent behavior.
- ❑ Good Test Management

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